# LTF Time of Flight Laser Distance Sensor Instruction Manual



Original Instructions p/n: 194135 Rev. J June 22, 2023

# Contents

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	amming H 20 mA (10 V)

Chapter 6 Specifications  Repeatability Performance  Dimensions	. 48 . 50
Chapter 7 Troubleshooting	51
Chapter 8 Sensor Menu Full Map	53
Chapter 9 Accessories  Cordsets  Brackets  RSD1 Remote Display.	. 55 . 56 . 57
Chapter 10 Banner Engineering Corp Limited Warranty	59

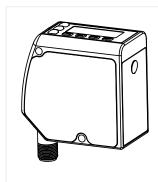
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#### **Chapter Contents**

Models	Ę
Overview	5
aser Description and Safety Information	. 7

# Chapter 1 Product Description

Laser distance sensor with both analog and discrete (switched) outputs



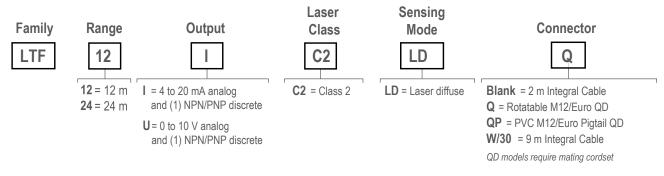
- · High-performance time of flight measurement
- Extended ranges up to 24 m
- · Reliably detects challenging targets
- · Fast setup with an intuitive interface

#### **WARNING:**



- · Do not use this device for personnel protection
- · Using this device for personnel protection could result in serious injury or death.
- This device does not include the self-checking redundant circuitry necessary to allow its use in
  personnel safety applications. A device failure or malfunction can cause either an energized (on)
  or de-energized (off) output condition.

# Models



NOTE: Some model combinations may not be available.

# Overview

The LTF Time of Flight Laser Distance Sensor is designed for precise, long-distance measurements. A 2-line LCD shows the real-time distance measurement, in either millimeters or inches, and the analog output measurement, in milliamps or volts, when the sensor is in Run mode.

See Factory Defaults for a list of sensor default settings.

Models with current or voltage analog outputs are available. This manual provides the display information and the navigation paths for the current models with the voltage model text in parentheses if it is different.

#### Features and Indicators



Three LED indicators provide an ongoing indication of the sensing status.

#### Analog Output LED Indicator

Solid Amber = Displayed distance is within the taught analog output window

Off = Displayed distance is outside the taught analog output window

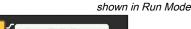
#### **Power LED Indicator**

Solid Green = Normal operation, power On and laser On Flashing Green (1 Hz) = Power On and laser Off (laser enable mode)

#### **Discrete Output LED Indicator**

Solid Amber = Discrete Output is On Off = Discrete Output is Off

## Display





The display is a 2-line, 8-character LCD. The main screen is the Run mode screen, which shows the real-time distance measurement and the analog output measurement.

#### **Buttons and Icons**

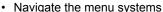
Use the sensor buttons **Down**, **Up**, **Enter**, and **Escape** to program the sensor and to access sensor information.

#### Down and Up Buttons



Press Down and Up to:







· Change individual digit values in distance based settings

When navigating the menu systems, the menu items loop.

Continued on page 7

#### Continued from page 6

# **Enter Button** Press Enter to: · Access the Sensor Menu from Run mode · Access the submenus · Move right one digit in distance based settings · Save changes In the Sensor Menu, a checkmark · in the lower right corner of the display indicates that pressing Enter accesses a submenu. Press Enter to save changes. New values flash rapidly and the sensor returns to the parent menu. **Escape Button** Press Escape to: Leave the current menu and return to the parent menu Return to Run mode from the Quick Menu. **IMPORTANT:** Pressing **Escape** discards any unsaved programming changes. In the Sensor Menu, a return arrow in the upper left corner of the display indicates that pressing Escape returns to the parent menu. Press and hold **Escape** for 2 seconds to return to Run mode from any menu or remote teach. A lock symbol displays in the upper left corner of the display to indicate when the sensor is locked.

# Laser Description and Safety Information

#### **CAUTION:**



- · Return defective units to the manufacturer.
- Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.
- Do not attempt to disassemble this sensor for repair. A defective unit must be returned to the manufacturer.

#### Class 2 Laser Models



#### CAUTION:

- · Never stare directly into the sensor lens.
- · Laser light can damage your eyes.
- · Avoid placing any mirror-like object in the beam. Never use a mirror as a retroreflective target.



#### For Safe Laser Use - Class 2 Lasers

- · Do not stare at the laser.
- Do not point the laser at a person's eye.
- Mount open laser beam paths either above or below eye level, where practical.
- Terminate the beam emitted by the laser product at the end of its useful path.

Reference IEC 60825-1:2007, Section 8.2.

#### Class 2 Lasers

Class 2 lasers are lasers that emit visible radiation in the wavelength range from 400 nm to 700 nm, where eye protection is normally afforded by aversion responses, including the blink reflex. This reaction may be expected to provide adequate protection under reasonably foreseeable conditions of operation, including the use of optical instruments for intrabeam viewing.

#### **Class 2 Laser Safety Notes**

Low-power lasers are, by definition, incapable of causing eye injury within the duration of a blink (aversion response) of 0.25 seconds. They also must emit only visible wavelengths (400 to 700 nm). Therefore, an ocular hazard may exist only if individuals overcome their natural aversion to bright light and stare directly into the laser beam.

FDA (CDRH) warning label (Class 2)

#### **LASER LIGHT**

DO NOT STARE INTO BEAM CLASS 2 LASER PRODUCT

Avoid exposure -

Avoid exposure laser light emitted from this aperture



#### **Chapter Contents**

Mount the Device	9
Wiring Diagrams	
Connecting to RSD1	10

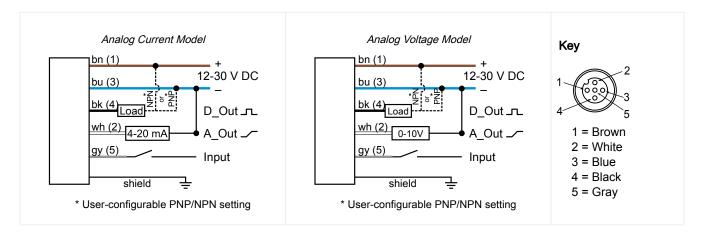
# Chapter 2 Sensor Installation

**NOTE:** Handle the sensor with care during installation and operation. Sensor windows soiled by finger-prints, dust, water, oil, etc. may create stray light that may degrade the peak performance of the sensor. Blow the window clear using filtered, compressed air, then clean as necessary using 70% isopropyl alcohol and cotton swabs or water and a soft cloth.

# Mount the Device

- 1. If a bracket is needed, mount the device onto the bracket.
- 2. Mount the device (or the device and the bracket) to the machine or equipment at the desired location. Do not tighten the mounting screws at this time.
- 3. Check the device alignment.
- 4. Tighten the mounting screws to secure the device (or the device and the bracket) in the aligned position.

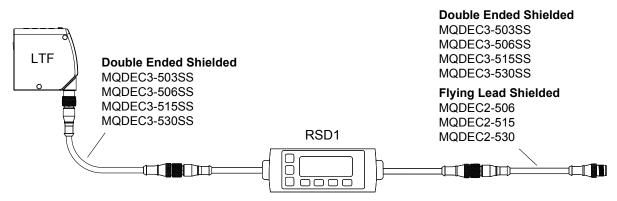
# Wiring Diagrams



# Connecting to RSD1

The following diagram depicts the connection of the LTF to the optional RSD1 accessory.

#### LTF to RSD1



Use these cordsets to connect the RSD1 to the LTF sensor or to other devices, such as PLC inputs, IO-Link masters, or control systems.

5-Pin Male Threaded and 5-Pin Female Quick Disconnect M12 Cordset with Shield—Double Ended				
Model	Length "L1"	Style	Pinout (Male)	Pinout (Female)
MQDEC3-503SS	0.91 m (2.99 ft)		2	1 (000)
MQDEC3-506SS	1.83 m (6 ft)			
MQDEC3-515SS	4.58 m (15 ft)	Female Straight/Male Straight	4	4 5
MQDEC3-530SS	9.2 m (30.2 ft)		3 6	
M12 x 1		M12 x 1  14.5  Ø 5.9  "L1"	1 = Brown 2 = White 3 = Blue	4 = Black 5 = Gray

5-Pin Threaded M12 Cordsets with Shield—Single Ended				
Model	Length	Style	Dimensions	Pinout (Female)
MQDEC2-506	2 m (6.56 ft)			- 0
MQDEC2-515	5 m (16.4 ft)		<del></del>	1 2
MQDEC2-530	9 m (29.5 ft)			1 = Brown 2 = White
MQDEC2-550	15 m (49.2 ft)	Straight	M12 x 1 –	
MQDEC2-575	23 m (75.44 ft)		M12 X 1 → ø 14.5 →	
MQDEC2-5100	30.5 m (100 ft)			3 = Blue 4 = Black 5 = Gray

#### Continued from page 10

5-Pin Threaded M12 Cordsets with Shield—Single Ended				
Model	Length	Style	Dimensions	Pinout (Female)
MQDEC2-506RA	2 m (6.56 ft)		22 Tup	
MQDEC2-515RA	5 m (16.4 ft)		32 Typ. [1.26"] 30 Typ. [1.18"]  M12 x 1	
MQDEC2-530RA	9 m (29.5 ft)			
MQDEC2-550RA	15 m (49.2 ft)	Right-Angle		
MQDEC2-575RA	23 m (75.44 ft)			
MQDEC2-5100RA	31 m (101.68 ft)			

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#### **Chapter Contents**

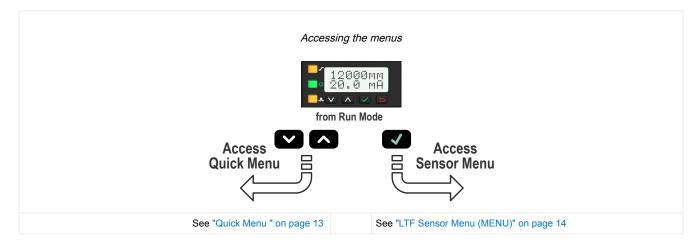
Quick Menu	13
TF Sensor Menu (MENU)	14
Remote Input	14
Locking and Unlocking the Sensor	16
Analog Output Menu (A_OUT)	
Discrete Output Menu (D_OUT)	
nput Menu (INPUT)	34
Measure Menu (MEASURE)	35
Display Menu (DISPLAY)	38
nformation Menu (INFO)	
Reset Menu (RESET)	41
Factory Default Settings	

# Chapter 3 Sensor Programming

Program the sensor using the buttons on the sensor or the remote input (limited programming options).

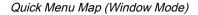
From Run mode, use the buttons to access the Quick Menu and the Sensor Menu. See "Quick Menu" on page 13 and "LTF Sensor Menu (MENU)" on page 14 for more information on the options available from each menu. For TEACH options, follow the TEACH instructions.

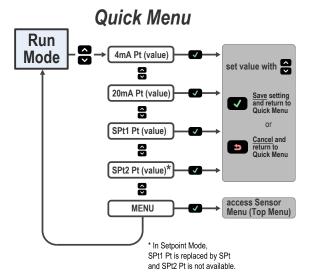
In addition to programming the sensor, use the remote input to disable the buttons for security, preventing unauthorized or accidental programming changes. See "Remote Input" on page 14 for more information.



# Quick Menu

The sensor includes a Quick Menu with easy access to view and change the analog and discrete output switch points. Access the Quick Menu by pressing **Down** or **Up** from Run mode. When in the Quick Menu, the current distance measurement displays on the first line and the menu name and the analog value alternate on the second line of the display. Press **Enter** to access the switch points. Press **Down** and **Up** to change each digit. Press **Enter** to move right one digit. After reviewing each digit, press **Enter** again to save the new value and return to the Quick Menu. Press **Cancel** to ignore any changes made if only some digits have been changed.

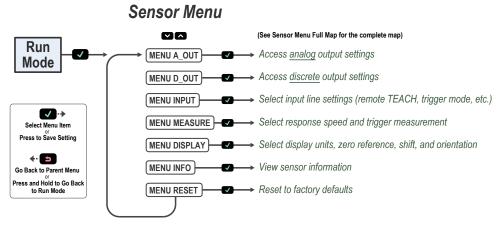




# LTF Sensor Menu (MENU)

Access the Sensor Menu by pressing **Enter** from Run mode. The Sensor Menu is also accessible from the Quick Menu: navigate to **MENU** and press **Enter**. The Sensor Menu includes several submenus that provide access to view and change sensor settings and to view sensor information.

#### Sensor Menu Basic Map



See "Sensor Menu Full Map" on page 53 and the Menu sections of this manual for more information.

# Remote Input

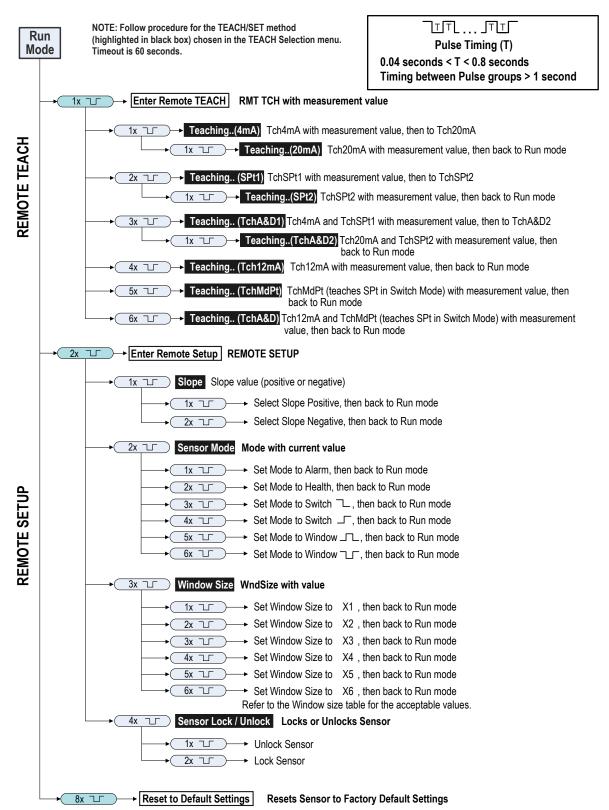
Use the remote input to program the sensor remotely. The remove input is disabled by default. Activate remote input using the buttons to navigate to the Input Type menu option.

The remote input provides limited programming options and is Active Low by default. For Active Low, connect the gray input wire to ground (0 V DC), with a remote switch connected between the wire and ground. To use the Active High function, configure the sensor for Active High using the buttons on the sensor, then connect the gray input wire to V+ (12 to 30 V DC). Pulse the remote input according to the diagram and the instructions provided in this manual.

The length of the individual programming pulses is equal to the value T: 0.04 seconds  $\leq T \leq 0.8$  seconds.

Exit remote programming modes by holding the remote input low for > 2 seconds, or waiting for the automatic 60-second timeout, or by pressing and holding **Escape** for 2 seconds. The sensor returns to Run mode without saving any new settings.

#### Remote Input Map



#### Remote TEACH window sizes

Variable	Remote TEACH Window Size (mm)		
variable	LTF12	LTF24	
X1	10	10	
X2	20	20	
X3	100	100	
X4	500	500	
X5	2000	2000	
X6	11950	23950	

# Locking and Unlocking the Sensor

Use the lock and unlock feature to prevent unauthorized or accidental programming changes. A lock symbol displays in the upper left corner of the display to indicate when the sensor is locked. When locked, the menus are available to view settings, but the values cannot be changed. The remote input is also disabled, except for the unlock function.

**Button Instructions**--To lock or unlock the sensor using the buttons, press and hold **Down** and **Escape** simultaneously for 3 seconds.

#### **Remote Input Instructions**

1. Access the setup mode.

Action	Result	
Double-pulse the remote input.	TTT	"REMOTE SETUP" displays.

#### 2. Access the lock/unlock function.

Action	Result	
Four-pulse the remote input.		"LOCK" and the current status (unlocked or locked) display.

#### 3. Lock or unlock the sensor.

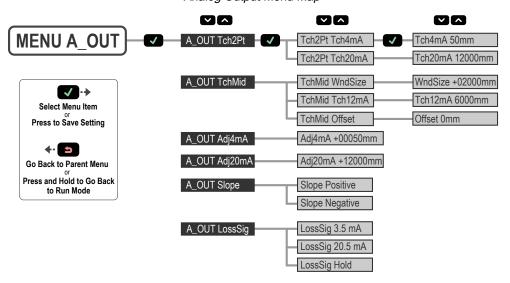
Action	Result	
Unlock: Single-pulse the remote line.	$\neg ^{T} \vdash$	"Unlocked" flashes and the sensor returns to Run mode. The sensor is unlocked.
Lock: Double-pulse the remote input.	TTT	"Locked" flashes and the sensor returns to Run mode. The sensor is locked and the lock symbol displays in the upper left cor- ner.

# Analog Output Menu (A\_OUT)

Use the Analog Output menu to view or change:

- · 4 mA (0 V) setpoint
- 20 mA (10 V) setpoint
- 12 mA (5 V) window
- Slope
- · Loss of signal behavior

#### Analog Output Menu Map



# TEACH 4 mA (0 V) and TEACH 20 mA (10 V)

The Tch4mA (Tch0V) and Tch20mA (Tch10V) options use targets to set the 4 mA (0 V) and 20 mA (10 V) to the desired setpoints. When using the buttons, only one value needs to be set if the second value is valid. When using the remote input, both values must be set.

Navigate: MENU > A\_OUT > Tch2Pt > Tch4mA (Tch0V) or navigate: MENU > A\_OUT > Tch2Pt > Tch20mA (Tch10V)

Remote input: Available

#### **Button Instructions**

1. Present the target.

Action	Result
Present the target. The target must be within the sensor's measurement range.	The target's analog output measurement and distance measurement values display.

2. Access the TEACH mode and TEACH the sensor.

Action	Result
	The selected TEACH mode and " <b>Teaching</b> " display while the sensor is being taught. <b>TEACH Accepted</b>
Navigate: MENU > A_OUT > Tch2Pt > Tch4mA (Tch0V) OR  Navigate: MENU > A_OUT > Tch2Pt > Tch20mA (Tch10V)	The new value is shown on the second line of the display and flashes before it is saved and the sensor returns to the parent menu.  TEACH Not Accepted  "FAIL" and a warning message display, and

3. Repeat steps 1 to 2 for the other setpoint, if desired.

#### **Remote Input Instructions**

Teaches both the 4 mA (0 V) and 20 mA (10 V) setpoints.

1. Access the TEACH mode.

Action		Result
Single-pulse the remote input.	7.	"RMT TCH" and the current measurement value display.

#### 2. Present the target.

Action	Result
Present the 4 mA (0 V) target.	"RMT TCH" and the target's measurement value display.

#### 3. TEACH the sensor.

Action		Result
Single-pulse the remote input.	٦٢٢	"Tch4mA (Tch0V) Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and then "Tch20mA (Tch10V)" and the current measurement value display.  TEACH Not Accepted  "FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.

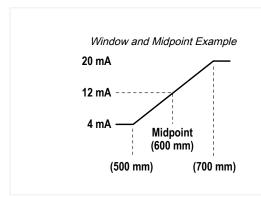
#### 4. Present the target.

Action	Result
Present the 20 mA (10 V) target.	"Tch20mA (Tch10V)" and the target's measurement value display.

#### 5. TEACH the sensor.

Action		Result
Single-pulse the remote input.	71	"Tch20mA (Tch10V) Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and the sensor returns to Run mode.  TEACH Not Accepted  "FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.

## Midpoint TEACH



The Midpoint TEACH uses both the window size and the 12 mA (5 V) setpoint to determine the actual measurement window. For example, a window of 200 mm with a 12 mA (5 V) setpoint of 600 mm places the measurement window from 500 mm to 700 mm. To use the Midpoint TEACH:

- 1. Set the window size.
- Set the measurement window using "TEACH 12 mA (5 V)" on page 20.

The Analog Output Midpoint TEACH and the Discrete Output Midpoint TEACH are independent settings (see "Midpoint TEACH" on page 26).

#### Window Size

The **A\_OUT > TchMid > WndSize** option sets the window size that the Midpoint TEACH uses to set the 4 mA (0 V) and 20 mA (10 V) setpoints.

The taught surface must be inside the defined sensing range, and at least one setpoint (with offset applied, if any) must be located within the sensing range.

The Analog Output window size is a different setting than the Discrete Output window size when defined using the push buttons.

Parameters	LTF12	LTF24
Window Size Minimum	10 mm	10 mm
Window Size Maximum	11950 mm	23950 mm
Range	50 mm to 12000 mm	50 mm to 24000 mm
Default Window Size	2000 mm	2000 mm

Navigate: MENU > A\_OUT > TchMid > WndSize

#### Remote Input: Available

1. Access the Window Size mode.

Method	Action	Result
Push Button	Navigate: MENU > A_OUT > TchMid > WndSize	"WndSize" and the current window size value display.

Continued on page 20

Continued from page 19

Method	Action		Result
Remete Input	a. Double-pulse the remote input to enter set- up mode.	$\neg $ $^{T}$ $^{T}$ $^{T}$	a. "REMOTE SETUP" displays.
Remote Input	b. Three-pulse the remote input to enter window size mode.		b. "WndSize" and the current window size value display.

#### 2. Set the window size.

Method	Action	Result
Push Button	<ul> <li>a. Use the <b>Up</b> and <b>Down</b> buttons to set the desired window size—the value changes in increments of 2.</li> <li>b. Press <b>Enter</b> to save the new value.</li> </ul>	<ul><li>a. "WndSize" and the new value display.</li><li>b. The new value flashes and the sensor returns to "TchMid Wnd-Size".</li></ul>
Remote Input (Sets A_OUT and D_OUT window Size)	Pulse the remote input 1 to 6 times to select the desired window size.  1 pulse: 10 mm  2 pulses: 20 mm  3 pulses: 100 mm  4 pulses: 500 mm  5 pulses: 2000 mm  6 pulses: 11950 mm for the LTF12; 23950 mm for the LTF24	The new value flashes and the sensor returns to Run mode.

## TEACH 12 mA (5 V)

The Tch12mA (Tch5V) option sets the midpoint that determines the actual measurement window.

Navigate: MENU > A\_OUT > TchMid > Tch12mA (Tch5V)

Remote Input: Available

#### **Button Instructions**

1. Present the target.

Ac- tion	Result
Present the The target's analog output measurement and distance tar- get.	e measurement values display.

2. Access the TEACH 12 mA (5 V) mode and TEACH the sensor.

Action	Result
Navigate: MENU > A_OUT > TchMid > Tch12mA (Tch5V).	"Tch12mA (Tch5V) Teaching" displays while the sensor is being taught.  TEACH Accepted
	The new value is shown on the second line of the display and flashes before it is saved and the sensor returns to "TchMid Tch12mA (Tch5V)".
	TEACH Not Accepted
	"FAIL" and a warning message display and the sensor returns to "Tch Mid Tch12mA (Tch5V)".

#### **Remote Input Instructions**

1. Access the TEACH mode.

Action		Result
Single-pulse the remote input.	¬Ţ⊏	"RMT TCH" and the current measurement value display.

#### 2. Present the target.

Ac- tion	Result
Present the "RMT TCH" and the target's measurement value display. tar-get.	

#### 3. TEACH the sensor.

Action		Result	
		"Tch12mA (Tch5V) Teaching" displays while the sensor is being taught.  TEACH Accepted	
Four-pulse the remote input.		The new value displays on the second line of the display, flashes, and the sensor returns to Run mode	
		TEACH Not Accepted	
		"FAIL" flashes, the sensor returns step 2, and "RMT TCH" displays.	

#### Window TEACH Offset

Use the **A\_OUT > TchMid > Offset** menu to set an offset from the taught distance used during a 12 mA (5 V) TEACH. By default, the value is 0 mm because the window is centered around the taught distance. A positive offset value always shifts the window towards the sensor.

# Adjust 4 mA (0 V)

The Adj4mA (Adj0V) option manually adjusts the distance at which the Analog Output is 4mA (0 V). The value is adjustable within the sensor's range. It is required to at least maintain the minimum window size.

Navigate: MENU > A\_OUT > Adj4mA (Adj0V)

Remote Input: Not available

Default: 50 mm

# Adjust 20 mA (10 V)

The Adj20mA (Adj10V) option manually adjusts the distance at which the Analog Output is 20 mA (10 V). The value is adjustable between the sensor's range. It is required to at least maintain the minimum window size.

Navigate: MENU > A\_OUT > Adj20mA (Adj10V)

Remote Input: Not available

Default: 12000 mm for LTF12, 24000 mm for LTF24

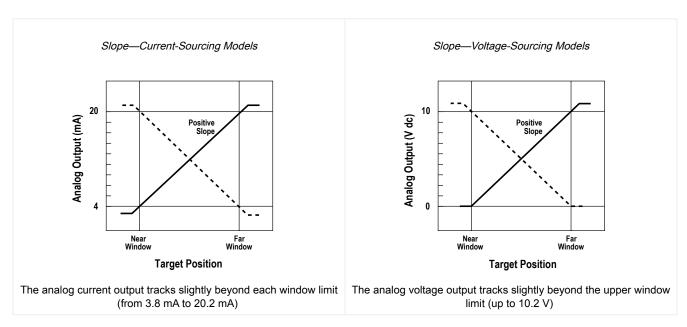
## Slope

The Slope option sets the slope as positive or negative. This swaps the 4 mA and 20 mA (0 V and 10 V) values.

Navigate: MENU > A\_OUT > Slope

Remote Input: Available

**Default:** Positive



#### 1. Access the slope setting.

Method	Action		Result
Push Button	Navigate: MENU > A OUT > Signe		"Slope" and the current setting display.
Remote Input	<ul><li>a. Double-pulse the remote input to enter set- up mode.</li><li>b. Single-pulse the remote input to ac- cess A_OUT Slope.</li></ul>		a. "REMOTE SETUP" displays.  b. "Slope" and the current setting display.

#### 2. Set the slope.

Method	Action		Result
Push Button	<ul><li>a. Use <b>Down</b> and <b>Up</b> to change the slope between Positive and Negative.</li><li>b. Press <b>Enter</b> to save the selection.</li></ul>		<ul><li>a. The selection flashes rapidly on the display.</li><li>b. The selection is saved and the sensor returns to "A_OUT Slope".</li></ul>
Remote Input	Positive slope: Single-pulse the remote input Negative slope: Double-pulse the remote input		The selection flashes rapidly on the display, and the sensor returns to Run mode.

## Loss of Signal

The LossSig option sets the Analog Output value used by the sensor during a loss of signal. When a signal is restored, measurement resumes.

Navigate: Menu > A\_Out > LossSig

Remote Input: Not available

**Default**: 3.5 mA (0 V)

Option	Description
3.5 mA (0 V)	The Analog Output switches to this value 2 seconds after a loss of signal. When advanced measurements are enabled, the Analog Output is updated to this value immediately upon the release of the trigger input. For Voltage models, this is 0 V. (Default)
20.5 mA (10.5 V)	The Analog Output switches to this value 2 seconds after a loss of signal. When advanced measurements are enabled, the Analog Output is updated to this value immediately upon the release of the trigger input. For Voltage models, this is 10.5 V.
Hold	The Analog Output holds the last value indefinitely during a loss of signal. When advanced measurements are enabled, the last value is held across the triggered measurement periods.

The Range advanced measurement behavior is affected by the Loss of Signal option. For additional information on advanced measurements, see "Trigger" on page 36. The Range advanced measurement tracks a maximum and a minimum during the measurement period, and calculates the range as follows:

Range = maximum distance - minimum distance

If the maximum and/or minimum measurements are outside of the taught setpoints, the Loss of Signal option determines how the range is calculated.

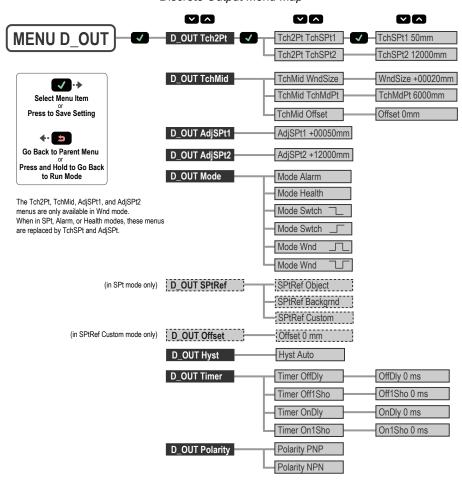
Option	Sensor Behavior in Range Mode
3.5 mA (0 V)	If the maximum or minimum measurement is outside of the taught setpoints, the sensor outputs 3.5 mA (0 V) to indicate an out of range measurement.
20.5 mA (10.5 V)	If the maximum or minimum measurement is outside of the taught setpoints, the sensor outputs 20.5 mA (10.5 V) to indicate an out of range measurement.
Hold	The sensor limits the maximum and minimum measurements so that they cannot exceed the taught setpoints.

# Discrete Output Menu (D\_OUT)

Use this menu to view or change

- · Setpoints
- · Midpoint
- Mode
- · Timers
- Polarity

#### Discrete Output Menu Map



#### Two-Point TEACH

The TchSpt1 and TchSPt2 options teach the desired switch points. When using the buttons, the switch points can be taught independently. Both values must be taught when using the remote input.

NOTE: When in Switch mode, see "TEACH Switch Point" on page 29.

Navigate: MENU > D OUT > Tch2Pt > TchSPt1 and navigate: MENU > D OUT > Tch2Pt > TchSPt2

Remote Input: Available

#### **Button Instructions**

1. Present the target.

Action	Result
Present the target. The target must be within the sensor's range	The target's analog output measurement and distance measurement value display.

#### 2. Access the TEACH mode and TEACH the sensor.

Action	Result
	The selected TEACH mode and " <b>Teaching</b> " display while the sensor is being taught. <b>TEACH Accepted</b>
Navigate: MENU > D_OUT > Tch2Pt > TchSPt1 OR	The new value is shown on the second line of the display and flashes before it is saved and the sensor returns to the parent menu.
Navigate: MENU > D_OUT > Tch2Pt > TchSPt2	TEACH Not Accepted
	"FAIL" and a warning message display, and the sensor returns to the parent menu.

3. Repeat steps 1 to 2 for the other switch point, if desired.

### **Remote Input Instructions**

1. Access the TEACH mode.

Action		Result
Single-pulse the remote input.	¬Ţ⊏	"RMT TCH" and the current switch point value displays.

#### 2. Present the target.

Action	Result
Present the switch point one target.	"RMT TCH" and the target's measurement value display.

#### 3. TEACH the sensor.

Action		Result
Double-pulse the remote input.	7,,,,,	"TchSPt1 Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and the sensor goes to "TchSPt2" and the current measurement value.  TEACH Not Accepted  "FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.

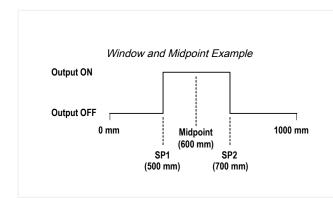
#### 4. Present the target.

Action	Result
Present the switch point two target.	"TchSPt2" and the target's measurement value display.

#### 5. TEACH the sensor.

Action		Result
Single-pulse the remote input.	¬Ţ⊏	"TchSPt2 Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and the sensor returns to Run mode.  TEACH Not Accepted  "FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.

## Midpoint TEACH



The Midpoint TEACH uses both the window size and the TEACH midpoint to determine the actual measurement window. For example, a window of 200 mm with a midpoint of 600 mm places the measurement window from 500 mm to 700 mm.

To use Midpoint TEACH:

- 1. Set the window size.
- 2. Set the measurement window using "TEACH Midpoint" on page 27.

The Discrete Output Midpoint TEACH and the Analog Output Midpoint TEACH are independent settings.

#### Window Size

The **D\_OUT > TchMid > WndSize** option sets the window size that the Midpoint TEACH uses to set the setpoint one and setpoint two thresholds.

The taught surface must be inside the defined sensing range, and at least one setpoint (with offset applied, if any) must be located within the sensing range.

The Discrete Output window size is a different setting than the Analog Output window size when defined using the push buttons.

Parameters	LTF12	LTF24
Window Size Minimum	10 mm	10 mm
Window Size Maximum	11950 mm	23950 mm
Range	50 mm to 12000 mm	50 mm to 24000 mm
Default Window Size	20 mm	20 mm

Navigate: MENU > D\_OUT > TchMid > WndSize

Remote Input: Available

1. Access the setup mode.

Method	Action		Result
Push Button	Navigate: MENU > D_OUT > TchMid > WndSize.		"WndSize" and the current window size value display.
Remote Input	<ul><li>a. Double-pulse the remote input to enter set- up mode.</li><li>b. Three-pulse the remote input to enter win- dow size mode.</li></ul>		a. "REMOTE SETUP" displays. b. "WndSize" and the current value display.

#### 2. Set the window size.

Method	Action	Result
Push Button	<ul> <li>a. Use <b>Down</b> and <b>Up</b> to set the desired window size—the value changes in increments of 2.</li> <li>b. Press <b>Enter</b> to save the new value.</li> </ul>	<ul><li>a. "WndSize" and the new value display.</li><li>b. The new value flashes and returns to "TchMid WndSize".</li></ul>
Remote In- put (Sets A_OUT and D_OUT window Size)	Pulse the remote input 1 to 6 times to select the desired window size.  1 pulse: 10 mm  2 pulses: 20 mm  3 pulses: 100 mm  4 pulses: 500 mm  5 pulses: 2000 mm  6 pulses: 11950 mm for the LTF12; 23950 mm for the LTF24	The new value flashes and the sensor returns to Run mode.

#### **TEACH Midpoint**

The TchMdPt option sets the midpoint that determines the actual measurement window.

Navigate: MENU > D\_OUT > TchMid > TchMdPt

Remote Input: Available

#### **Button Instructions**

1. Present the target.

Action	Result
Present the target.	The target's analog output measurement and distance measurement value display.

2. Access the TEACH midpoint mode and TEACH the sensor.

Action	Result
Navigate: MENU > D_OUT > TchMid > TchMdPt	"TchMdPt Teaching" displays while the sensor is being taught.  TEACH Accepted
	The new value is shown on the second line of the display and flashes before it is saved and the sensor returns to "TchMid Tch-MdPt".
	TEACH Not Accepted
	"FAIL" and a warning message display, and the sensor returns to "TchMid TchMdPt".

#### **Remote Input Instructions**

1. Access the TEACH mode.

Action	Result
Single-pulse the remote input.	 "RMT TCH" and the current measurement value display.

#### 2. Present the target.

Action	Result
Present the target.	"RMT TCH" and the target's measurement value display.

#### 3. TEACH the sensor.

Action	Result
Five-pulse the remote input.	"TchMdpt Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and the sensor returns to Run mode.  TEACH Not Accepted  "FAIL" and a warning message display, the sensor returns to step 2, and "RMT TCH" displays.

#### Window TEACH Offset

Use the **D\_OUT > TchMid > Offset** menu to set an offset from the taught distance used during a Midpoint TEACH. By default, the value is 0 mm because the window is centered around the taught distance. A positive offset value always shifts the window towards the sensor.

# Adjust Switch Point One

The AdjSPt1 option manually adjusts the value of the switch point one threshold for the Discrete Output when the sensor is in Window mode. The value is adjustable within the sensor's range. It is required to be maintain the minimum window size between switch points. This menu is not available when the sensor is in Switch, Alarm, or Health mode.

Navigate: MENU > D\_OUT > AdjSPt1

Remote Input: Not available

Default: 50 mm

### Adjust Switch Point Two

The AdjSPt2 option manually adjusts the value of the switch point two threshold for the Discrete Output when the sensor is in Window mode. The value is adjustable with the sensor's range. It is required to be maintain the minimum window size between switch points. This menu is not available when the sensor is in Switch, Alarm, or Health mode.

Navigate: MENU > D\_OUT > AdjSPt2

Remote Input: Not available

Default: 12000 mm for LTF12; 24000 mm for LTF24

## **TEACH Switch Point**

The TchSPt option teaches the distance at which the switch point threshold is placed when the Discrete Output is in Switch mode. This menu is not available when the sensor is in Window, Alarm, or Health mode.

Navigate: MENU > D\_OUT > TchSPt

Remote Input: Available

#### **Button Instructions**

1. Present the target.

Action	Result
Present the target. The target must be within the sensor's range.	The target's analog output measurement and distance measurement value display.

2. Access the switch point TEACH mode and TEACH the sensor.

Action	Result
Navigate: <b>MENU</b> > <b>D_OUT</b> > <b>TchSPt</b>	"TchSPt Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value is shown on the second line of the display and flashes before it is saved and the sensor returns to "D_OUT TchSPt".
	TEACH Not Accepted
	"FAIL" and a warning message display, and the sensor returns to "D_OUT TchSPt".

#### Remote Input Instructions

- 1. Verify the sensor is in Switch mode.
- 2. Access the TEACH mode.

Action		Result
Single-pulse the remote input.	¬ <u>⊺</u> ⊏	"RMT TCH" and the current measurement value display.

3. Present the target.

Action	Result
Present the target.	"RMT TCH" and the target's measurement value display.

#### 4. TEACH the sensor.

Action	Result
Five-pulse the remote input.	"TchSPt Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and the sensor returns to Run mode.  TEACH Not Accepted  "FAIL" flashes, the sensor returns to step 3, and "RMT TCH" displays.

## **Adjust Switch Point**

The AdjSPt option manually adjusts the value of the switch point threshold for the discrete output when the sensor is in Switch mode. The value is adjustable within the sensor's range. This menu is not available when the sensor is in Window, Alarm, or Health mode.

Navigate: MENU > D\_OUT > AdjSPt

Remote Input: Not available

Default: 50 mm

#### Mode

The Mode option sets the output to the desired mode.

Navigate:MENU > D\_OUT > Mode

Remote Input: Available

Default: Wnd (Discrete Output is On while a target is detected between the SPt1 and SPt2 thresholds) mode

The following table describes the sensor modes.

Mode	Description
Alarm	Alarm Mode: The Discrete Output is Off while a target is detected by the sensor at any distance. When a loss of signal occurs, the Discrete Output is On.  This mode has no associated thresholds.
Health	Health Mode: The Discrete Output is On while a target is detected by the sensor at any distance. When a loss of signal occurs, the Discrete Output is Off.  This mode has no associated thresholds.
Swtch	<b>Switch Mode:</b> The Discrete Output is On while a target is detected nearer than the switch point threshold. When a target is detected farther than the switch point threshold or the signal is lost, the Discrete Output is Off.
Swtch	<b>Switch Mode:</b> The Discrete Output is Off while a target is detected nearer than the switch point threshold. When a target is detected farther than the switch point threshold or the signal is lost, the Discrete Output is On.

Continued on page 31

#### Continued from page 30

Mode	Description
Wnd	Window Mode: The Discrete Output is On while a target is detected between the SPt1 and SPt2 thresholds. (Default) When a target is detected outside the SPt1 and SPt2 thresholds or the signal is lost, the Discrete Output is Off.
Wnd_	<b>Window Mode:</b> The Discrete Output is Off while a target is detected between the SPt1 and SPt2 thresholds. When a target is detected outside the SPt1 and SPt2 thresholds or the signal is lost, the Discrete Output is On.

### Remote Input Instructions

1. Access the setup mode.

Action		Result
Double-pulse the remote input.	ŢŢŢ	"REMOTE SETUP" displays.

#### 2. View the current mode.

Action		Result
Double-pulse the remote input.	TTTT	The current mode displays.

#### 3. Program the sensor.

Action	Result	
Pulse the remote input 1 to 6 times to select the desired mode.	The selected mode flashes and the sensor returns to Run mode.	

Pulses		Mode
1	¬ <u>†</u> _	Alarm
2		Health
3		Swtch
4		Swtch

Continued on page 32

Continued from page 31

Pulses	Mode	
5	Wnd	
6	Wnd	

## Switch Point Reference (SPtRef)

The SPtRef menu only displays for a discrete output when it is set to switch mode. This setting cannot be changed with remote teach.

- Object (default). Object mode automatically optimizes the switching threshold just past the taught distance, farther away from the sensor's face.
- Background. Background mode automatically optimizes the switching threshold just in front of the taught distance, closer to the sensor's face.
- **Custom**. Custom mode allows the user to define the location of the switching threshold relative to a taught distance using the Offset menu that appears only after selecting Custom Switch Point Reference.

In **Object** or **Background**, the distance between the taught surface and the switching threshold varies depending on measurement stability. Use object mode when teaching an object if a change in state is required when the object is no longer present. Use background mode when teaching background so that the output state changes when a new object is in front of the background.

Navigate: MENU > D\_OUT > SPtRef

Remote Input: Not available

Default: Object

#### Switch Point TEACH Offset

Use this menu to set an offset from the taught distance after a switch point TEACH, if SPtRef is set to Custom.

By default, the value is 0 mm. A positive offset value always shifts the threshold towards the sensor.

Navigate: MENU > D\_OUT > TchMd > Offset

Remote Input: Not available

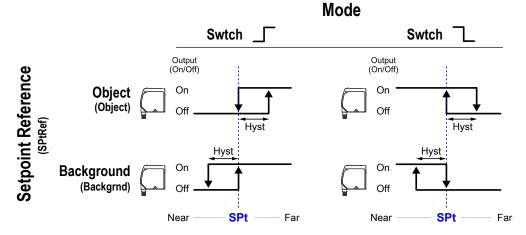
Default: 0 mm

# Switch Point Hysteresis

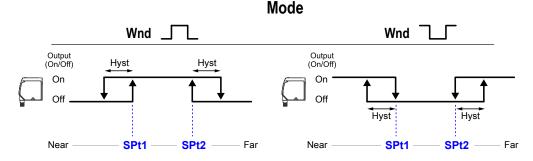
With the default setting of AUTO, the hysteresis value applied at each threshold is automatically calculated and set based on target, distance and measurement repeatability, with a 10 mm minimum setting.

By default, the hysteresis is applied away from the sensor. Changing the SPt Ref setting from Object to Background changes the direction of the hysteresis.

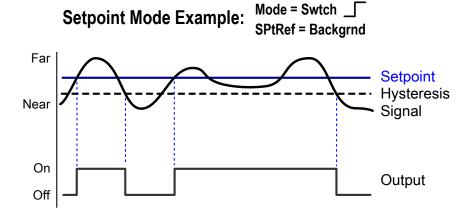
How hysteresis affects the sensor output based on the discrete output switchpoint mode and the setpoint reference mode



How hysteresis affects the two discrete output window modes



How hysteresis affects the output on/off points when if the sensor is configured with mode = Swtch\_/- and SPtRef configured as Backgrnd



Press the up button to manually select a constant hysteresis value between 2 mm and 11950 mm for the LTF12 and between 2 mm and 23950 mm for the LTF24 models.

Navigate: MENU > D\_OUT > Hyst

Remote Input: Not available

Default: Auto

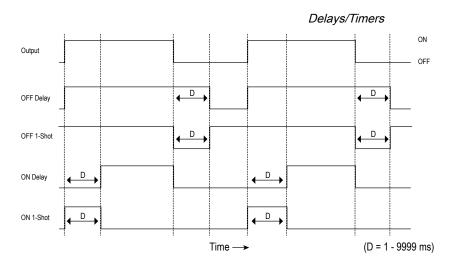
#### Timer

The Timer option sets the delays and timers. On/Off Delays and On/Off One-Shot timers can be programmed between 1 to 9999 ms (a value of 0 disables the delay/timer). The following figure defines how the delays/timers affect the output behavior.

Navigate: MENU > D\_OUT > Timer

Remote Input: not available

Default: 0 ms for all timers



Some combinations of delays/timers are not allowed. The programming menu automatically disables invalid combinations of delays/timers. The following table shows the allowable combinations of delays/timers.

	Off Delay	Off One-Shot Timer	On Delay	On One-Shot Timer
Off Delay (OffDly)	OK	OK	OK	N/A
Off One-Shot Timer (Off1Sho)	OK	OK	N/A	N/A
On Delay (OnDly)	OK	N/A	ОК	ОК
On One-Shot Timer (On1Sho)	N/A	N/A	OK	ОК

# Polarity

The Polarity option sets the discrete output polarity to either PNP (current sourcing) or NPN (current sinking). The physical wiring of the sensor and the sensor polarity setting must match.

Navigate: MENU > D\_OUT > Polarity

Remote Input: Not available

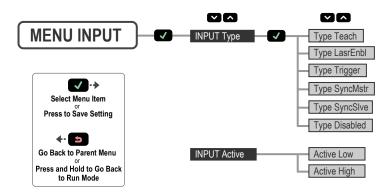
Default: PNP

# Input Menu (INPUT)

Use this menu to view or change the:

- · Multi-function input type
- · Active state of the remote input

#### Input Menu map



## Input Type

The Type option sets the input type.

Navigate: MENU > INPUT > Type

Remote Input: Not available

Default: Disabled

Input Type	Description	
Teach	The remote input is used to TEACH and program the sensor.	
LasrEnbl	The remote input is used to control when the laser emitter is On/Off.	
Trigger	The remote input is used to trigger advanced measurements To enable advanced measurements, the Input Type option must be set to Trigger (see Key definition for "{keyrefName}" not found in the DITA map.).	
SyncMstr	The remote input is used as the Master Sync output to an attached Slave sensor (see Key definition for "{keyrefName}" not found in the DITA map.).	
SyncSive	The remote input is used as the Slave Sync input from an attached Master sensor (see Key definition for "{keyrefName}" not found in the DITA map.).	
Disabled	The remote input is disabled. (Default)	

# Input Active

The Active option sets the active state of the remote input. Use the Active options to change the active input to Low or High.

Navigate: MENU > INPUT > Active

Remote Input: Not available

Default: Low

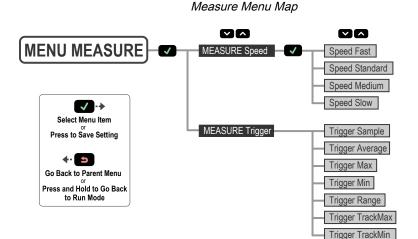
Input Active	Description	
Low	The remote input detects low (0 V) inputs and high-to-low transitions. (Default)	
High	The remote input detects high (V+) inputs and low-to-high transitions.	

# Measure Menu (MEASURE)

Use this menu to view or change the:

Speed

#### Trigger



# Speed

The Speed option sets the speed at which the measurement is calculated. This process uses averaging in the digital processing of the signal to calculate the measurement. A slower speed increases the response time of the sensor but improves the repeatability. Refer to the repeatability specifications for each speed.

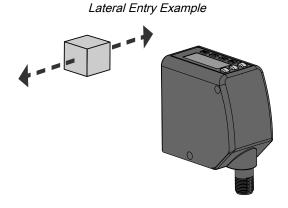
Navigate: MENU > MEASURE > Speed

Remote Input: Not available

Default: Medium

Speed	Response Time *	Lateral Entry
Fast	1.5 ms	5.5 ms
Standard	8 ms	16 ms
Medium	32 ms	48 ms
Slow	256 ms	288 ms

<sup>\*</sup> Response time triples when using Master/Slave mode.



# Trigger

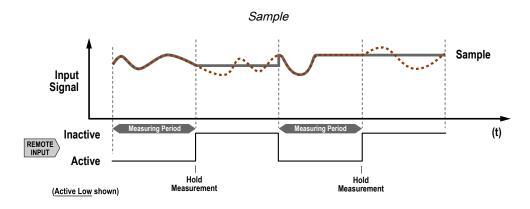
The Trigger option sets the advanced measurement that is calculated when a trigger event is detected on the remote input. The analog output updates with the new advanced measurement on each trigger event. To use these Trigger options, the sensor Input Type option must be set to Trigger; see " Input Type " on page 35.

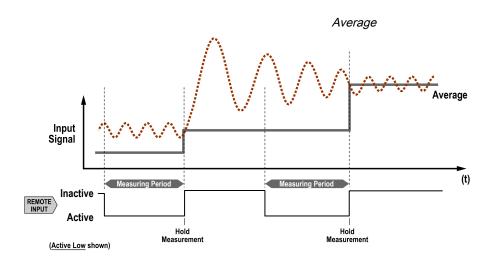
Navigate: MENU > MEASURE > Trigger

Remote Input: Not available

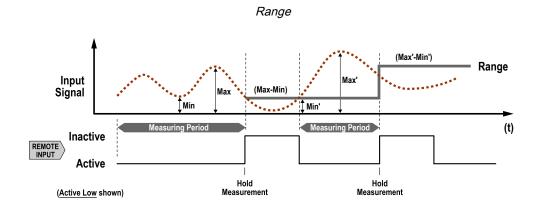
Default: Sample

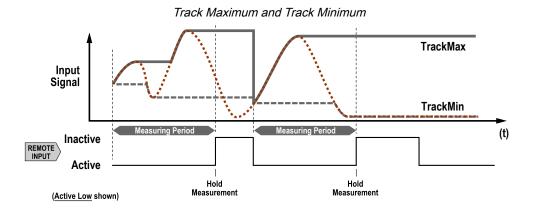
Trigger	Description
Sample	The current distance at the time of the trigger event. (Default) The Analog Output tracks the sample values during the measuring period.
Average	The average distance since the last trigger event.
Maximum (Max)	The maximum distance since the last trigger event.
Minimum (Min)	The minimum distance since the last trigger event.
Range	The difference between the maximum and minimum distance since the last trigger event. For additional information on the Range measurement behavior when the maximum or minimum distance is outside of the taught setpoints, see "Loss of Signal" on page 23.
TrackMax	The maximum distance since the last trigger event. The Analog Output tracks new maximum values during the measurement period.
TrackMin	The minimum distance since the last trigger event. The Analog Output tracks new minimum values during the measurement period.





# Input Signal Maximum Measuring Period Measuring Period Measuring Period (t) REMOTE INPUT Active Active Hold Measurement Measurement Measurement Measurement Measurement

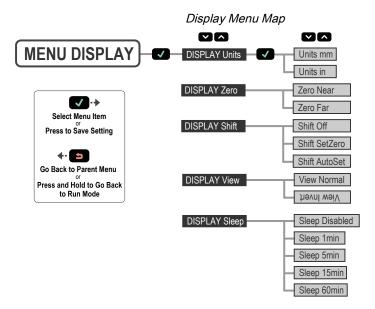




# Display Menu (DISPLAY)

Use this menu to view or change the:

- · Display units
- · Display orientation
- · Sleep mode settings



#### Units

The Units option sets the displayed units to millimeters (mm) or inches (in).

Navigate: MENU > DISPLAY > Units

Remote Input: Not available

Default: mm

#### Zero and Shift

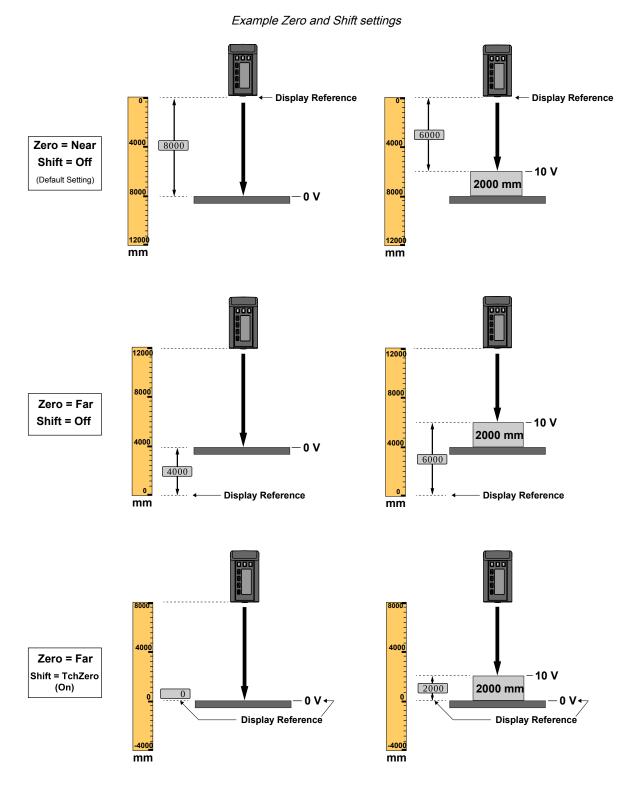
Use the **Display Zero** menu to select the zero-reference location. The default is 0 = the face of the sensor.

- Near—0 = the face of the sensor; the measurement increases further from the sensor
- Far—0 = maximum range; the measurement increases closer to the sensor

Use the **Display Shift** menu to select whether the sensor shifts the zero-reference location based on the last TEACH process. The default is Off (0).

- Off—0 = the face of the sensor or the maximum range, depending on the zero setting
- SetZero—Sets the current distance as its new zero reference location. This process is independent of teaching analog or discrete set points.
- AutoSet—Shifts the zero-reference location at the taught distance during any analog or discrete setting teach.

This figure illustrates three examples of how changes to the zero and shift settings affect what distance readout is shown on the display when in 2-pt TEACH mode. Changes to the zero setting affect the direction in which the distance increases. Turning the shift setting on sets the taught location as the reference point for any distance measurement.



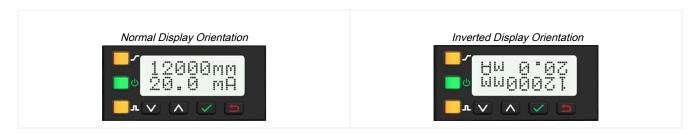
#### View

The View option sets the display orientation of the sensor. Invert the display for applications where the device is mounted upside down. This rotates the display 180°. The Down and Up buttons do not change when the display is inverted.

Navigate: MENU > DISPLAY > View

Remote Input: Not available

#### **Default:** Normal



#### Sleep

The Sleep option sets when the display is put to sleep. Four timing options are available: 1, 5, 15, or 60 minutes. Sleep mode is disabled by default. Sleep occurs in Run mode and any menu. To wake the sensor and return to the last viewed mode or menu, press any button.

Navigate: MENU > DISPLAY > Sleep

Remote Input: Not available

Default: Disabled

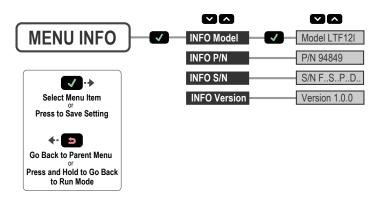
### Information Menu (INFO)

Use this menu to view model, part number (P/N), serial number (S/N), and firmware version (Version) information. Select one of these options to view specific information for your sensor. This information is read-only.

Navigate: MENU > INFO

Remote Input: Not available

#### Information Menu Map



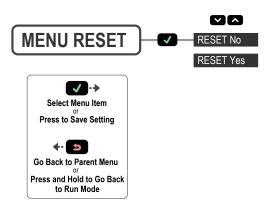
## Reset Menu (RESET)

Use this menu to restore the sensor to the factory default settings.

Navigate: MENU > RESET. Select Yes to apply the factory defaults; select No to return to the Reset option without changing any sensor settings.

Remote Input: Eight-pulse the remote input

#### Reset Menu Map



# **Factory Default Settings**

Analog Output Settings	LTF12	LTF24
Adjust 4 mA (0 V)	50 mm	50 mm
Adjust 20 mA (10 V)	12000 mm	24000 mm
Loss of Signal	3.5 mA (0 V)	3.5 mA (0 V)
Slope	Positive	Positive
Window Size	2000 mm	2000 mm

Discrete Output Settings	LTF12	LTF24
Adjust Switch Point One	50 mm	50 mm
Adjust Switch Point Two	12000 mm	24000 mm
Mode	Wnd	Wnd
Polarity	PNP	PNP
Timer	0 ms for all timers	0 ms for all timers
Window Size	20 mm	20 mm

Input Settings	Value
Input Active	Low
Input Type	Disabled

Measure Settings	Value
Speed	Medium
Trigger	Sample

Display Settings	Value
Sleep	Disabled
Units	mm
Zero	Near
Shift	Off
View	Normal

# Chapter 4 Sync Master/Slave

Two LTF sensors may be used together in a single sensing application. To eliminate crosstalk between the two sensors, configure one sensor to be the master and one to be the slave. In this mode, the sensors alternate taking measurements and the response speed triples.

- 1. Configure the first sensor as the master; navigate: MENU > INPUT > Type > SyncMstr.
- 2. Configure the second sensor as the slave; navigate: MENU > INPUT > Type > SyncSive.
- 3. Connect the gray (input) wires of the two sensors together.

If using a combination of Class 1 and Class 2 laser models, the Class 1 laser model must be used as the master.

# Blank page

TEACH Analog Output and Discrete Output Switch Points Together	. 45
TEACH Analog Output and Discrete Output Midpoints Together	46

# Chapter 5

# Additional Remote TEACH Procedures

# TEACH Analog Output and Discrete Output Switch Points Together

Use the following procedure to teach identical Analog Output and Discrete Output switch points at the same time using the remote input. This feature is not available using the buttons.

1. Access the TEACH mode.

Action		Result
Single-pulse the remote input.	¬ <u>⊺</u> ⊏	"RMT TCH" and the current measurement value display.

#### 2. Present the target.

Action	Result
Present the switch point one target.	"RMT TCH"and the target's measurement value display.

#### 3. TEACH the sensor.

Action		Result
Three-pulse the remote input.		"TchA&D1 Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and then "TchA&D2" and the current measurement value display.
		TEACH Not Accepted  "FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.

#### 4. Present the target.

Action	Result
Present the switch point two target.	"TchA&D2" and the target's measurement value display.

#### 5. TEACH the sensor.

Action		Result
		"TchA&D2 Teaching" displays while the sensor is being taught.
		TEACH Accepted
Single-pulse the remote input.	$\neg$ $^{T}$	The new value displays on the second line of the display, flashes, and the sensor returns to Run mode.
		TEACH Not Accepted
		"FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.

# TEACH Analog Output and Discrete Output Midpoints Togeth-

#### er

Use the following procedure to teach an identical Analog Output 12 mA (5 V) point and Discrete Output midpoint (switch point) at the same time using the remote input. This feature is not available using the buttons. Note that if the window sizes and/or offsets were set independently (using the buttons), the windows taught using the following procedure could be different.

When the Discrete Output is set to Switch Mode, the SPt TEACH is executed with SPtRef=Custom and Offset=0 mm.

#### 1. Access the TEACH mode.

Action	Result	
Single-pulse the remote input.	$\neg \bot \vdash$	"RMT TCH" and the current measurement value display.

#### 2. Present the target.

Action	Result	
Present the midpoint (switch point) target.	"RMT TCH"and the target's measurement value display.	

#### 3. TEACH the sensor.

Action		Result	
Six-pulse the remote input.		"TchA&D Teaching" displays while the sensor is being taught.  TEACH Accepted  The new value displays on the second line of the display, flashes, and the sensor returns	
on pales are remote input.		to Run mode.  TEACH Not Accepted	
		"FAIL" flashes, the sensor returns to step 2, and "RMT TCH" displays.	

Repeatability Performance	48
Dimensions	50

#### Chapter 6 **Specifications**

#### Supply Voltage

12 V DC to 30 V DC

#### Power and Current Consumption (Exclusive of Load)

Normal Run Mode: < 2.1 W

Current consumption < 85 mA at 24 V DC

#### Supply Protection Circuitry

Protected against reverse polarity and transient overvoltages

Die-cast zinc housing; acrylic window

#### **Maximum Torque**

2.6 N·m (23.0 in-lbs)

#### Sensing Beam

Visible red, 660 nm

#### Sensing Range - LTF12

90% White Target: 50 mm to 12000 mm 18% Gray Target: 50 mm to 11000 mm 6% Black Target: 50 mm to 7000 mm

#### Sensing Range - LTF24

90% White Target: 50 mm to 24000 mm 18% Gray Target: 50 mm to 18000 mm 6% Black Target: 50 mm to 11000 mm

#### **Ambient Light Immunity**

> 40000 lux

#### Delay at Power Up

2 seconds

#### Measurement Output Rate

0.5 ms

#### **Output Configuration**

Analog output: 4 to 20 mA or 0 to 10 V, depending on model Discrete output rating: Discrete NPN/PNP is user-configurable

#### **Output Ratings**

Discrete Output: 100 mA maximum (protected against continuous overload and short circuit)

OFF-state leakage current (PNP): < 10 µA at 30 V OFF-state leakage current (NPN): < 200 µA at 30 V

Output saturation voltage (PNP outputs): < 3 V at 100 mA

Output saturation voltage (NPN outputs): < 1.6 V at 100 mA

Analog current output (LTF...I Models):1 kΩ maximum at 24 V; maximum load resistance = [(Vcc-4.5)/0.02 Ω]

Analog voltage output (LTF...U Models): 2.5 kΩ minimum load resistance

#### Remote Input

Allowable Input Voltage Range: 0 to Vcc

Active Low (internal weak pullup—sinking current): High State > 4.3 V at 740 μA maximum; Low State < 1.3 V at 800 μA

Active High (internal weak pulldown—sourcing current): High State > 4.3 V at 1.7 mA maximum; Low State < 1.3 V at 1.6 mA maximum

#### Minimum Window Size, Analog and Discrete

10 mm

#### **Boresighting**

100 mm radius at 12000 mm

#### Temperature Effect

50 mm to 12000 mm: ±0.25 mm/°C (typical) >12000 mm: ±0.5 mm/°C (typical)

#### Resolution

LTF12: < 0.3 mm to 3 mm 1TF24 < 0.3 mm to 4 mm

Resolution measured as twice repeatability with white target at slow response speed at 20 °C. See repeatability curves for more detail.

#### **Beam Spot Size**

6.5 mm at 50 mm

10 mm at 7500 mm

12.5 mm at 12000 mm

35 mm at 24000 mm

Beam spot size is calculated as 1.6 times the D4σ measured diameter

#### Response Time

Fast: 1.5 ms Standard: 8 ms Medium: 32 ms Slow: 256 ms

#### Storage Conditions

-30 °C to +65 °C (-22 °F to +149 °F)

#### Operating Conditions

-20 °C to +55 °C (-4 °F to +131°F)

90% at +55 °C maximum relative humidity (non-condensing)

MIL-STD-202G, Method 213B, Condition I (100G 6x along X, Y, and Z axes, 18 shocks), with device operating

#### Repeatability

See Performance Curves

#### **Environmental Rating**

IP67: NEMA 6

#### Vibration

MIL-STD-202G, Method 201A (Vibration: 10 Hz to 55 Hz, 0.06 inch (1.52 mm) double amplitude, 2 hours each along X, Y and Z axes), with device operating

#### **Application Note**

#### Certifications



Banner Engineering BV Park Lane, Culliganlaan 2F bus 3 1831 Diegem, BELGIUM



Turck Banner LTD Blenheim House Blenheim Court Wickford, Essex SS11 8YT GREAT BRITAIN



#### Linearity/Accuracy

Reflectance	LTF12		LTF24		
Reliectance	±10 mm	±25 mm	±25 mm	±50 mm	±100 mm
6% Black Card	4 m	7 m	7 m	8 m	11 m
18% Gray Card	7 m	11 m	11 m	13 m	18 m
90% White Card	12 m	-	24 m	-	-

For optimum performance, allow 15 minutes for the sensor to warm up

#### Required Overcurrent Protection



**WARNING:** Electrical connections must be made by qualified personnel in accordance with local and national electrical codes and regulations.

Overcurrent protection is required to be provided by end product application per the supplied table.

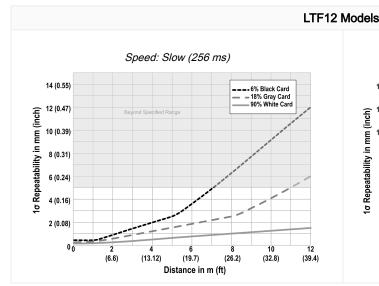
Overcurrent protection may be provided with external fusing or via Current Limiting, Class 2 Power Supply.

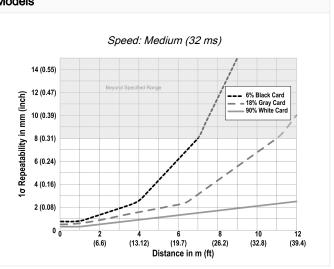
Supply wiring leads < 24 AWG shall not be spliced.

For additional product support, go to www.bannerengineering.com.

Supply Wiring (AWG)	Required Overcurrent Protection (A)	Supply Wiring (AWG)	Required Overcurrent Protection (A)
20	5.0	26	1.0
22	3.0	28	0.8
24	1.0	30	0.5

# Repeatability Performance

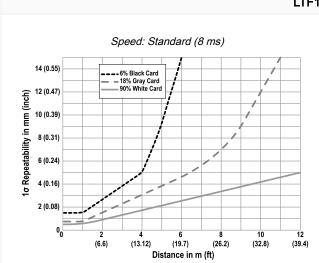


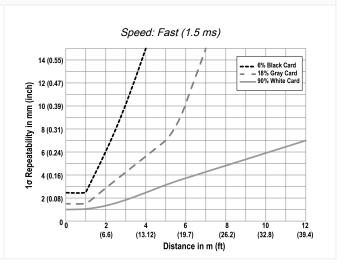


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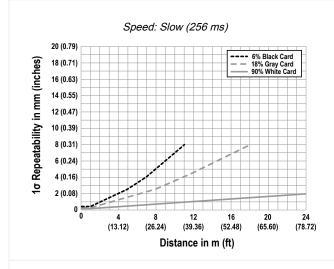
#### Continued from page 48

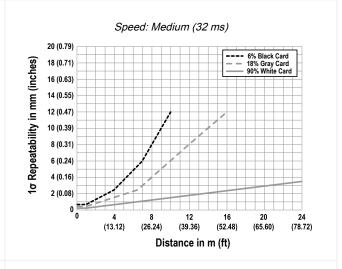
#### LTF12 Models

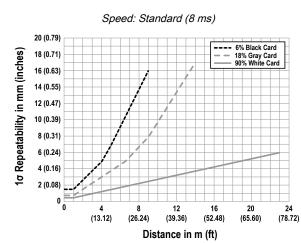


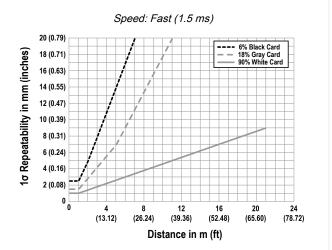


#### LTF24 Models

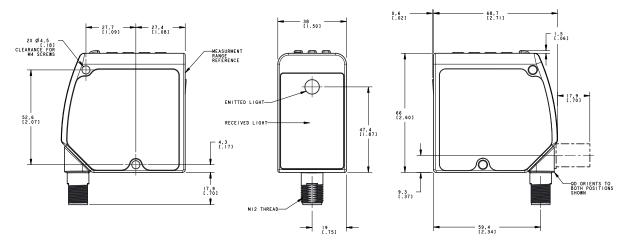








# **Dimensions**



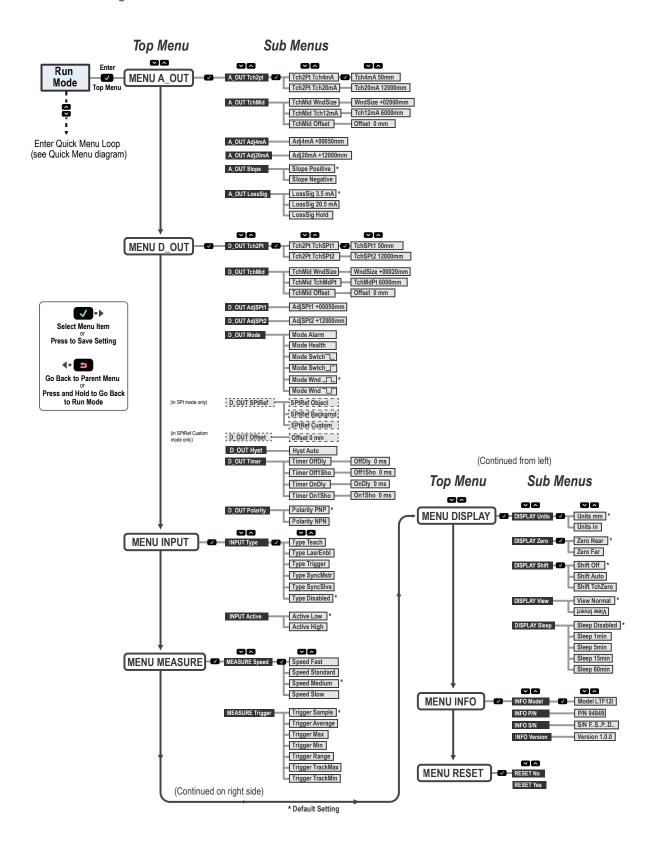
All measurements are listed in millimeters [inches], unless noted otherwise.

# Chapter 7 Troubleshooting

Message/Indicator	Description	Resolution
Fail/Out of Range	The TEACH failed, the target is out of range. The target might have moved out of range after the TEACH process began.	TEACH the target within the measurement range.
Fail/OfSt Out of Range	The TEACH failed. The target is in range but the offset value caused the setpoint(s) to be out of range.	Adjust the offset value or target distance to keep the setpoint(s) within the measurement range.
MIN Wnd xx mm (xx in)	The adjusted or taught window size is too small; the minimum window size is displayed.	The sensor automatically adjusts the window size to maintain the minimum window size and completes the adjust or TEACH operation.
xxxx < NEAR	The threshold (xxxx) is less than the minimum sensing range. xxxx could be 4mA Pt (0V Pt), 20mA Pt (10V Pt) or SPt1.	The desired window size is maintained, but the usable portion of the window is restricted to be within the defined sensing range.
xxxx > FAR	The threshold (xxxx) is greater than the maximum sensing range. xxxx could be 4mA Pt (0V Pt), 20mA Pt (10V Pt) or SPt2.	The desired window size is maintained, but the usable portion of the window is restricted to be within the defined sensing range.
OutRnge	The target is out of range, too dark, or the sensor is not measuring.	Move the target within the measurement range.
< NEAR	During RUN mode the target is detected, but is inside the NEAR measuring range.	The sensor can reliably detect targets up to the face of the sensor, and the Discrete Output state is valid. The Analog Output cannot be used to measure distances inside the NEAR measuring range.
Power LED is flashing green	The sensor input is set to laser enable and the input is not active.	See " Input Type " on page 35.
All LEDs are flashing	The laser shuts off, the Power LED flashes green, the Output LEDs flash amber at 1 Hz, and the display is blank.  The sensor has experienced a fault.	Contact Banner Engineering to resolve.
Type Sync Slave	The slave mode sensor does not see the master's pulse.	Make sure that the master mode sensor is configured and functioning properly. Check the input wire connection between the master and slave.

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# Chapter 8 Sensor Menu Full Map

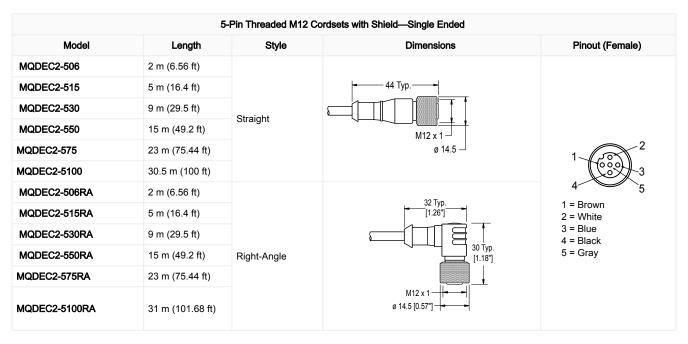


Cordsets	55
Brackets	56
RSD1 Remote Display	57

# Chapter 9 Accessories

## Cordsets

All measurements are listed in millimeters, unless noted otherwise.



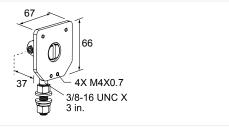
5-Pin Male Threaded and 5-Pin Female Quick Disconnect M12 Cordset with Shield—Double Ended				
Model	Length "L1"	Length "L1" Style		Pinout (Female)
MQDEC3-503SS	0.91 m (2.99 ft)		2 4	1 000 3
MQDEC3-506SS	1.83 m (6 ft)			
MQDEC3-515SS	4.58 m (15 ft)	Female Straight/Male Straight		
MQDEC3-530SS	9.2 m (30.2 ft)		5	
M12 x 1  14.5  47.4  "L1"			1 = Brown 2 = White 3 = Blue	4 = Black 5 = Gray

## **Brackets**

All measurements are listed in millimeters, unless noted otherwise.

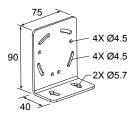
#### **SMBLTFFA**

- Swivel plate bracket
- 5 mm stainless steel



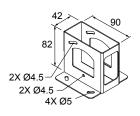
#### **SMBLTFL**

- · Right-angle bracket
- 12 gauge stainless steel



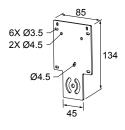
#### **SMBLTFU**

- · Enclosed bracket
- 16 gauge stainless steel



#### **SMBAMSLTFP**

- AMS mounting pattern
- 12 gauge stainless steel



#### **SMBAMSLTFIP**

- · Includes the mounting plate and two protective windows
- 90 plus degree rotation
- Window frames are black anodized aluminum; mounting plate is stainless steel
- The mounting plate, SMBAMSLTFP, can be ordered separately
  The replacement window, RWAMSLTF, can be ordered separately



# RSD1 Remote Display

Use the optional RSD1 for remote monitoring and configuring compatible devices.

Refer to the RSD1 instruction manual (p/n 199621) or quick start guide (p/n 199622) for more information. See "Accessories" on page 55 for the required cordsets.

RSD1 Remote Display					
Model	Output A and B	Dimensions	Male	Wiring	
RSD1QP	Configurable	78.0 [3.07] 28.0 [1,10] 68.0 [2.68]	2 4 3 5	<ol> <li>Brown</li> <li>White</li> <li>Blue</li> <li>Black</li> <li>Gray</li> </ol>	

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50

# Chapter 10 Banner Engineering Corp Limited Warranty

Banner Engineering Corp. warrants its products to be free from defects in material and workmanship for one year following the date of shipment. Banner Engineering Corp. will repair or replace, free of charge, any product of its manufacture which, at the time it is returned to the factory, is found to have been defective during the warranty period. This warranty does not cover damage or liability for misuse, abuse, or the improper application or installation of the Banner product.

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For patent information, see www.bannerengineering.com/patents.

Document title: LTF Time of Flight Laser Distance Sensor Instruction Manual

Part number: 194135

Revision: J

Original Instructions

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June 22, 2023





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